

A SHORT PROOF OF DE SHALIT'S CUP PRODUCT FORMULA

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ABSTRACT. We give a short proof of a formula of de Shalit, expressing the cup product of two vector valued one forms of the second kind on a Mumford curve in terms of Coleman integrals and residues. The proof uses the notion of double indices on curves and their reciprocity laws.

1. INTRODUCTION

In [dS88] de Shalit proved a formula for the cup product of two vector valued differential forms on a Mumford curve. This is based on an earlier partial result of his [dS89] for two holomorphic differentials. This formula was later reproved by Iovita and Spiess [IS03]. The goal of this short note is to give an alternative short proof of de Shalit's formula, based on the theory of the double index [Bes00, Section 4].

Let us state de Shalit's result. Let K be a finite extension of \mathbb{Q}_p . Consider a Mumford curve \mathcal{H}/Γ , where $\Gamma \subset \mathrm{PGL}_2(K)$ is a Schottky group and $\mathcal{H} \subset \mathbb{P}_K^1$ is the rigid analytic space obtained by removing the limit points of Γ . Let V be a finite dimensional K -vector space with a representation of Γ . The group Γ acts on the space of V -valued differential forms on \mathcal{H} , $\Omega^1(\mathcal{H}, V)$, by the rule

$$\gamma\left(\sum \omega_i v_i\right) = \sum (\gamma^{-1})^* \omega_i \gamma(v_i)$$

(compare [dS88, 1.1]). We let it act by the same formula on spaces of functions. A V -valued differential one-form ω on \mathcal{H} with values in V is Γ -invariant if $\gamma(\omega) = \omega$ for every $\gamma \in \Gamma$. It is of the second kind if its residues (with values in V , computed coordinatewise, in any basis), are 0 at any point $z \in \mathcal{H}$. Let $\langle \cdot \rangle$ be a Γ -invariant bilinear form on V . The cup product of two Γ -invariant V -valued one forms of the second kind ω and η can be described by the formula

$$\omega \cup \eta = \sum_{z \in \Gamma \backslash \mathcal{H}} \mathrm{Res}_z \langle F_\omega, \eta \rangle,$$

where F_ω is any primitive of ω locally near z , which exists (formally) because of the residue of ω at z is 0, and is independent of the choice of the primitive because the residue of η at z is 0. Note that the expression to be summed indeed depends only on z modulo Γ .

An open annulus is a rigid space isomorphic to the space $s < |z| < r$. An orientation on an annulus may be described as a choice of a parameter z as above, with two parameters considered equivalent if they give the residue, as defined below. An annulus together with an orientation is called an oriented annulus. A differential form ω on an oriented annulus e has a residue $\mathrm{Res}_e \omega$ such that $\mathrm{Res} \sum a_i z^i dz = a_{-1}$.

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It can be shown that there are only two orientations, giving residues differing by multiplication by -1 . By choosing a basis for V the residue extends easily to V valued differential forms.

We now recall [dS89, Definition 2.5] that the action of Γ on \mathcal{H} has a good fundamental domain in the following sense: There are pairwise disjoint closed K -rational discs B_i and C_i , $i = 1, \dots, g$ and open annuli b_i , c_i , and elements $\gamma_i \in \Gamma$, such that the following holds:

- (1) The γ_i freely generate Γ .
- (2) The unions $B_i \cup b_i$ and $C_i \cup c_i$ are open discs, still pairwise disjoint.
- (3) For each i , γ_i maps B_i isomorphically onto the complement of $C_i \cup c_i$ and b_i isomorphically onto c_i .
- (4) The complement of $\bigcup_i (B_i \cup b_i \cup C_i)$ is a fundamental domain for Γ .

We give the annuli c_i and b_i the orientation given by the discs C_i and B_i respectively, i.e., one given by parameters extending to $C_i \cup c_i$ and taking the value 0 on C_i (respectively with b_i and B_i). Thus, c_i is oriented in the same way as in [dS88, 1.5] while b_i is oriented in the reversed direction to loc. cit. (the b_i 's do not show up in the formula). With this choice, $\gamma_i : b_i \rightarrow c_i$ is orientation reversing.

de Shalit's formula involves Coleman integration of holomorphic V -valued 1 forms. While this can be described in a completely elementary way since we are dealing with subdomains of the projective line [GvdP80, P. 41], we will use the more involved theory of Coleman [CdS88] and adapt it to our case by choosing a basis of V and then integrate coordinate by coordinate. This is clearly independent of the choice of a basis because Coleman integration is linear (up to constant). The key property of Coleman integration is its functoriality. It immediately implies that from the property $\gamma\omega = \omega$ we may deduce that for any $\gamma \in \Gamma$ the function $\gamma(F_\omega) - F_\omega$ is constant. We can now state the main theorem.

Theorem 1.1 ([dS88, Theorem 1.6]). *With the data above we have*

$$\omega \cup \eta = \sum_i \langle \gamma_i F_\omega - F_\omega, \text{Res}_{c_i} \eta \rangle - \langle \text{Res}_{c_i} \omega, \gamma_i F_\eta - F_\eta \rangle .$$

The main ingredient in the present proof is the theory of double indices and their reciprocity laws on curves [Bes00, Section 4]. We need a very easy extension of this theory to vector valued differential forms. Once this has been described, the proof is an easy computation.

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2. DOUBLE INDICES OF VECTOR VALUED DIFFERENTIAL FORMS

In this section we describe a rather straightforward generalization of the theory of double indices [Bes00, Section 4] to the case of vector valued one forms. The extension is fairly trivial since we consider only constant coefficients. We work over \mathbb{C}_p for convenience.

Let A be either the field of meromorphic functions in the variable z over \mathbb{C}_p or the ring of rigid analytic functions on an annulus $\{r < |z| < s\}$ over \mathbb{C}_p . Let $A_{\log} := A[\log(z)]$ and let $A_{\log,1} \subset A_{\log}$ be the subspace of $F \in A_{\log}$ which are linear in $\log(z)$, a condition which is equivalent to $dF \in Adz$.

Definition 2.1. [Bes00, Proposition 4.5] The double index, $\text{ind}(\) : A_{\log,1} \times A_{\log,1} \rightarrow \mathbb{C}_p$ is the unique antisymmetric bilinear pairing such that $\text{ind}(F, G) = \text{Res } FdG$, whenever $F \in A$.

Suppose now that C is a proper smooth curve over \mathbb{C}_p with good reduction, and that U is a rigid analytic space obtained from C by removing discs D_i of the form $|z_i| \leq r$, with $r < 1$, where the reduction of z_i is a local parameter near a point x_i of the reduction. Let us call these domains *simple domains*. To the disc D_i corresponds the annulus e_i given by the equation $r < |z_i| < 1$, which is contained in U and oriented by z_i .

Choose a branch of the p -adic logarithm. Given a rigid one form $\omega \in \Omega^1(U)$, Coleman's theory provides us with a unique up to constant, locally analytic function F_ω on U with the property that $dF_\omega = \omega$. Restricted to the annuli e_i these clearly belong to $A_{\log,1}$ and one can therefore define, for two such functions F_ω and F_η the double index $\text{ind}_{e_i}(F_\omega, F_\eta)$. It follows from [Bes00, Lemma 4.6] that this index depends only on the orientation. One of the main technical results of [Bes00] is the following.

Proposition 2.2 ([Bes00, Proposition 4.10]). *We have $\sum_i \text{ind}_{e_i}(F_\omega, F_\eta) = \Psi(\omega) \cup \Psi(\eta)$, where $\Psi : H_{\text{dR}}^1(U) \rightarrow H_{\text{dR}}^1(C)$ is a certain projection.*

We will only need the following immediate Corollary, which follows because $H_{\text{dR}}^1(\mathbb{P}^1/\mathbb{C}_p) = 0$.

Corollary 2.3. *Suppose that $C = \mathbb{P}^1$. Then, in the situation above, $\sum_i \text{ind}_{e_i}(F_\omega, F_\eta) = 0$.*

We can now extend the theory to vector valued differential forms in a rather trivial way. Suppose we are given a finite dimensional \mathbb{C}_p -vector space with a bilinear form \langle , \rangle .

Definition 2.4. Choose bases $\{v_i\}$ and $\{u_i\}$ for V . Suppose that the V -valued Coleman functions F_ω and F_η are written as

$$\begin{aligned} F_\omega &= \sum F_{\omega_i} v_i, \\ F_\eta &= \sum F_{\eta_i} v_i. \end{aligned}$$

Then, the local index $\text{ind}_e(F_\omega, F_\eta)$ is given by

$$\text{ind}_e(F_\omega, F_\eta) = \sum_{i,j} \text{ind}_e(F_{\omega_i}, F_{\eta_j}) \langle v_i, u_j \rangle.$$

It is easy to check that this definition does not depend on the choice of bases. An easy consequence of the definitions is the following.

Proposition 2.5. *Suppose that $\text{Res}_e \omega = 0$. Then $\text{ind}_e(F_\omega, F_\eta) = \text{Res}_e \langle F_\omega, \eta \rangle$ while $\text{ind}_e(F_\eta, F_\omega) = -\text{Res}_e \langle \eta, F_\omega \rangle$.*

We now restrict to the case $C = \mathbb{P}^1$ but consider more general subdomains U , obtained by removing closed discs $D_i = |z - \alpha_i| = r_i$, including the case of removing a point when $r_i = 0$. For each i we consider an annulus e_i in U surrounding D_i , in such a way that the open discs $D_i \cup e_i$ are still disjoint. We will call the e_i the *annuli ends* of U . It is easy to see that U can be obtained by gluing simple domains $U' \in \mathbb{P}^1$ along annuli. Note that the U' 's are glued along annuli with reversed orientations.

Given $\omega \in \Omega^1(U, V)$ one can define its Coleman integral F_ω first on each of the U' 's as before and then by adjusting constants along the annuli. The intersection graph of the U' 's is a tree so there is always a way of choosing an integral globally. This construction coincides with the definition of Coleman integrals in [GvdP80].

Proposition 2.6. *In the situation described above we have, for any rigid V -valued one-form on U , $\sum_i \text{ind}_{e_i}(F_\omega, F_\eta) = 0$.*

Proof. The case V trivial and U simple is Corollary 2.3. We next consider the case $U = U'_1 \cup U'_2$ with U'_1 and U'_2 glued along an annulus e . Since e has reversed orientations when considered in U'_1 and U'_2 , the double index ind_e has a reverse sign in these two cases by [Bes00, Lemma 4.6]. Thus, the result for U follows from those for U'_1 and U'_2 . Now, the case of a general U , still with trivial V , follows immediately. The general case follows by choosing bases. \square

Proposition 2.7. *Let e be an annulus in \mathcal{H} and let $\gamma \in \Gamma$. For $\omega \in \Omega^1(e, V)$ let F_ω be its integral. Then γF_ω is a Coleman integral of $\gamma(\omega)$ on $\gamma(e)$, furthermore, If η is another such form, then we have*

$$\text{ind}_e(F_\omega, F_\eta) = \pm \text{ind}_{\gamma(e)}(\gamma(F_\omega), \gamma(F_\eta)),$$

depending on whether γ is orientation reversing or saving.

Proof. We choose a basis $\{v_i\}$ of V and we let $\{u_i\}$ be the dual basis with respect to \langle , \rangle . Then, since \langle , \rangle is Γ -invariant, the bases $\{\gamma(v_i)\}$ and $\{\gamma(u_i)\}$ are also dual to each other. This implies that if $F_\omega = \sum f_i v_i$ while $F_\eta = \sum g_i u_i$, then

$$\text{ind}_e(F_\omega, F_\eta) = \sum_i \text{ind}_e(f_i, g_i)$$

and

$$\text{ind}_{\gamma(e)}(\gamma(F_\omega), \gamma(F_\eta)) = \sum_i \text{ind}_{\gamma(e)}((\gamma^{-1})^* f_i, (\gamma^{-1})^* g_i).$$

But by [Bes00, Lemma 4.6] we have, for each i ,

$$\text{ind}_e(f_i, g_i) = \pm \text{ind}_{\gamma(e)}((\gamma^{-1})^* f_i, (\gamma^{-1})^* g_i),$$

depending on whether γ^{-1} is orientation reversing or preserving, and the result follows immediately from this. \square

3. THE PROOF

Proof of Theorem 1.1. By the remark following Equation (5) in [dS88] we may assume that b_i and c_i contain no poles of ω and η . Consider the domain $\mathcal{F} = \mathbb{P}^1 - \bigcup_i (B_i \cup C_i)$, which is of the type considered in Section 2, and its annuli ends are the b_i and c_i . It follows from the description of the fundamental domain for Γ that $\mathcal{F} - \bigcup_i (c_i \cup b_i)$ contains exactly one out of every Γ class of every singularity of either forms. It follows that

$$\omega \cup \eta = \sum_{x \in \mathcal{F}} \text{Res}_x \langle F_\omega, \eta \rangle = \sum_{x \in \mathcal{F}} \text{ind}_x(F_\omega, F_\eta) = - \sum_i (\text{ind}_{b_i}(F_\omega, F_\eta) + \text{ind}_{c_i}(F_\omega, F_\eta))$$

where the last equality follows from Proposition 2.6. We now observe that since γ_i is orientation reversing we have by Proposition 2.7 that $\text{ind}_{b_i}(F_\omega, F_\eta) = - \text{ind}_{c_i}(\gamma_i F_\omega, \gamma_i F_\eta)$.

Therefore

$$\begin{aligned}
& - (\text{ind}_{b_i}(F_\omega, F_\eta) + \text{ind}_{c_i}(F_\omega, F_\eta)) \\
& = \text{ind}_{c_i}(\gamma_i F_\omega, \gamma_i F_\eta) - \text{ind}_{c_i}(F_\omega, F_\eta) \\
& = \text{ind}_{c_i}(\gamma_i F_\omega - F_\omega, \gamma_i F_\eta) + \text{ind}_{c_i}(F_\omega, \gamma_i F_\eta - F_\eta) \\
& = \text{Res}_{c_i} \langle \gamma_i F_\omega - F_\omega, \gamma_i \eta \rangle - \text{Res}_{c_i} \langle \omega, \gamma_i F_\eta - F_\eta \rangle \quad \text{by Proposition 2.5} \\
& = \langle \gamma_i F_\omega - F_\omega, \text{Res}_{c_i} \eta \rangle - \langle \text{Res}_{c_i} \omega, \gamma_i F_\eta - F_\eta \rangle.
\end{aligned}$$

The theorem follows immediately. \square

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